

FORM PTO-1449
(Rev. 7-80)U.S. DEPARTMENT OF COMMERCE
PATENT AND TRADEMARK OFFICEAtty. Docket No.
14395Serial No.
10/615,595**LIST OF PRIOR ART CITED BY APPLICANT**
(Use several sheets if necessary)APPLICANT
KHAJEPOUR et al.FILING DATE
July 9, 2003GROUP
3652

U.S. PATENT DOCUMENTS

EXAMINE R INITIAL		DOCUMENT NUMBER							DATE	NAME	CLASS	SUBCLASS	FILING DATE IF APPROPRIATE
/DUJ/	AA	3	2	8	6	8	5	1	11-22-1966	Sperg			
/DUJ/	AB	3	4	9	7	0	8	3	02-24-1970	Anderson			
/DUJ/	AC	3	6	3	1	7	3	7	01-04-1976	Wells			
	AD	4	6	6	6	3	6	2	05-19-1987	Landsberger et al.			
/DUJ/	AE	4	6	8	3	7	7	3	08-04-1987	Diamond			
	AF	4	9	7	6	5	8	2	12-11-1990	Clavel			
	AG	5	3	1	3	8	5	4	03-23-1994	Akeel			
/DUJ/	AH	5	3	3	3	5	1	4	08-02-1994	Toyama et al.			
/DUJ/	AI	5	9	6	7	7	2	9	10-19-1999	Foes			

OTHER PRIOR ART (Including Author, Title, Date, Pertinent Pages, Etc.)

/DUJ/	BB	"Delta, a Fast Robot with Parallel Geometry", R. Clavel, Proc. Int. Symposium on Industrial robots, April 1988, pp. 91-100.
/DUJ/	BB	"Kinematics of a Three-DOF Platform with Three Extensible Limbs", Lung-Wen Tsai, Recent Advances in Robot Kinematics, pp. 401-409.
/DUJ/	BB	"A Smart Kinesthetic Interactive Platform", M. Griffiths et al., Advances in Robot Kinematics and Computed Geometry, pp. 459-464.
/DUJ/	BD	"Development of an Ultrahigh speed Robot FALCON using Wire Drive System", S. Kawamura et al., IEEE International Conference on Robotics and Automation 1995, pp. 215-220.

EXAMINER

/Donald Underwood/

DATE CONSIDERED

07/03/2007

EXAMINER: Initial if reference considered, whether or not citation is in conformance with MPEP 802. Draw line through citation if not in conformance and not considered. Include copy of this form with next communication to applicant.

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